

News in jet algorithms: SISCone and anti- k_t

Grégory Soyez

Brookhaven National Laboratory

G.P. Salam, G. Soyez, JHEP 05 (2007) 086 [arXiv:0704.0292]

M. Cacciari, G.P. Salam, G. Soyez, JHEP 04 (2008) 063 [arXiv:0802.1189]

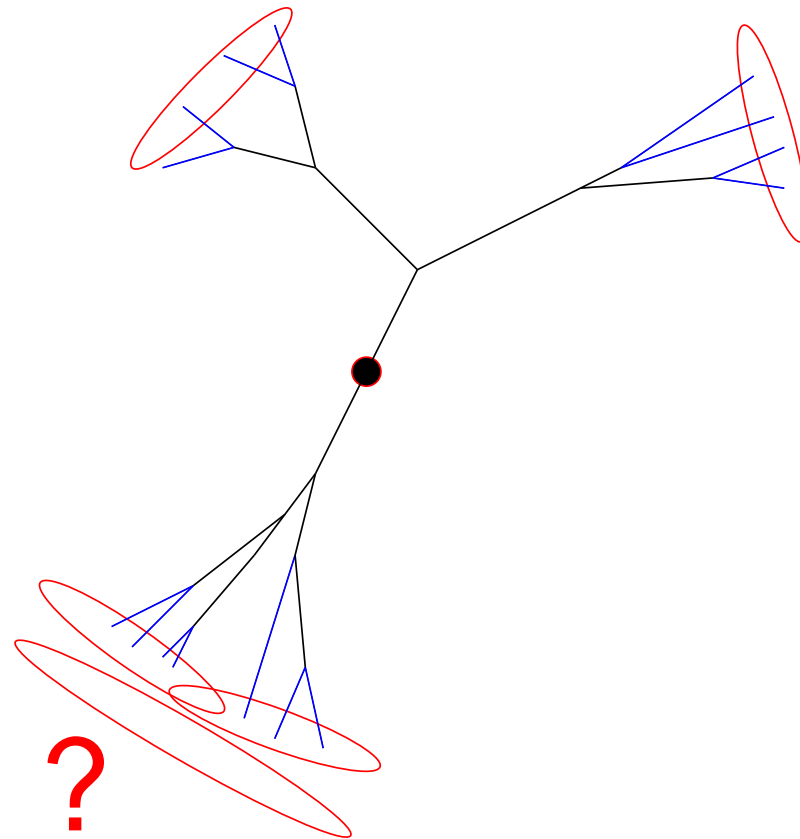
Aim: Study hard processes

- QCD backgrounds, top quark physics
- Higgs, physics beyond the standard model

Define jets: parton \leftrightarrow jet

But: partons are ambiguous

Hence: Multiple definitions of a “jet”



Class 1: recombination	Class 2: cone
Successive recombinations of the “closest” ^(a) pair of particle	find directions of energy flow ≡ stable cones ^(b)
Nice perturbative behaviour	Small sensitivity to soft radiation (UE,PU)
Often used in $e^\pm e^\pm, e^\pm p$	Often used in pp

(a) Distance:

$$k_t: d_{i,j} = \min(k_{t,i}^2, k_{t,j}^2)(\Delta\phi_{i,j}^2 + \Delta y_{i,j}^2)$$

$$\text{Aachen/Cam.}: d_{i,j} = \Delta\phi_{i,j}^2 + \Delta y_{i,j}^2$$

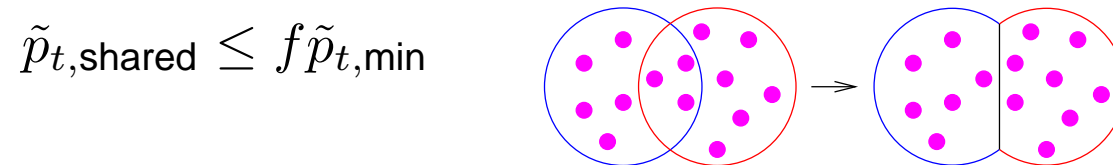
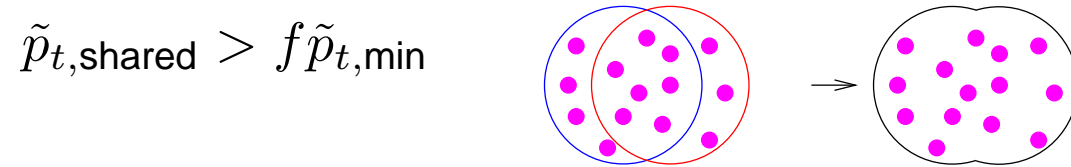
(b) stable cones (radius R) such that:

the total momentum of its contents points in the direction of its centre

- Seeded (iterative) approaches: iterate from an initial position until stable
 - seed = initial particle
 - seed = midpoint between stable cones found at first step
 - One has to deal with overlapping stable cones: 2 subclasses
-

- Seeded (iterative) approaches: iterate from an initial position until stable
 - seed = initial particle
 - seed = midpoint between stable cones found at first step

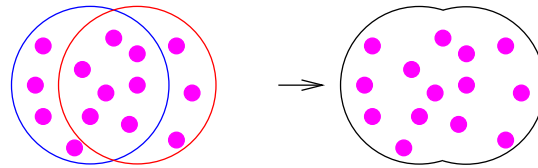
Class 2(a): cone with split-merge (ex.: JetClu, Atlas, MidPoint):



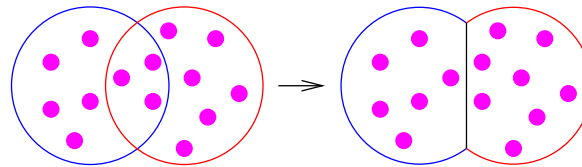
- Seeded (iterative) approaches: iterate from an initial position until stable
 - seed = initial particle
 - seed = midpoint between stable cones found at first step

Class 2(a): cone with split-merge (ex.: JetClu, Atlas, MidPoint):

$$\tilde{p}_{t,\text{shared}} > f\tilde{p}_{t,\text{min}}$$



$$\tilde{p}_{t,\text{shared}} \leq f\tilde{p}_{t,\text{min}}$$



Class 2(b): cone with progressive removal (ex.: Iterative Cone)

- iterate from the hardest seed
- remove the stable cone as a jet and start again

Idea: “regular/circular” jets

SNOWMASS, Tevatron 1990 (i.e. old!):

Several important properties that should be met by a jet definition are [3]:

1. Simple to implement in an experimental analysis;
2. Simple to implement in the theoretical calculation;
3. Defined at any order of perturbation theory;
4. Yields finite cross section at any order of perturbation theory;
5. Yields a cross section that is relatively insensitive to hadronization.

i.e. usable by theoreticians (e.g. finite perturbative results)
and experimentalists (e.g. fast enough)

This talk:

- Seeded cone algorithms miss stable cones \Rightarrow theoretical problems
- That can be solved keeping experimental usefulness

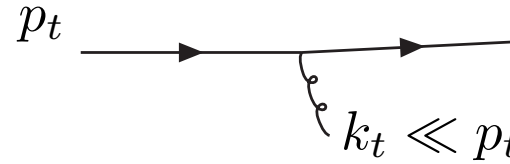
QCD probability for gluon bremsstrahlung at angle θ and \perp -mom. k_t :

$$dP \propto \alpha_s \frac{d\theta}{\theta} \frac{dk_t}{k_t}$$

Two divergences:



Collinear



Soft

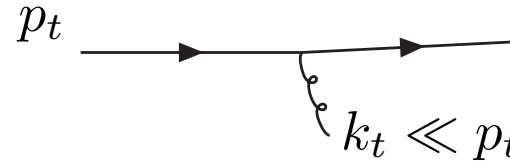
QCD probability for gluon bremsstrahlung at angle θ and \perp -mom. k_t :

$$dP \propto \alpha_s \frac{d\theta}{\theta} \frac{dk_t}{k_t}$$

Two divergences:



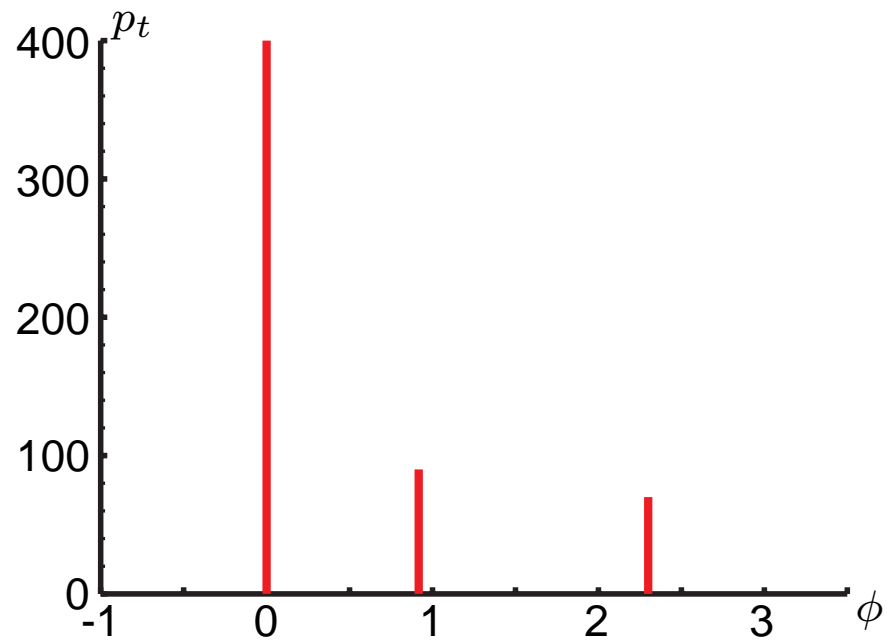
Collinear

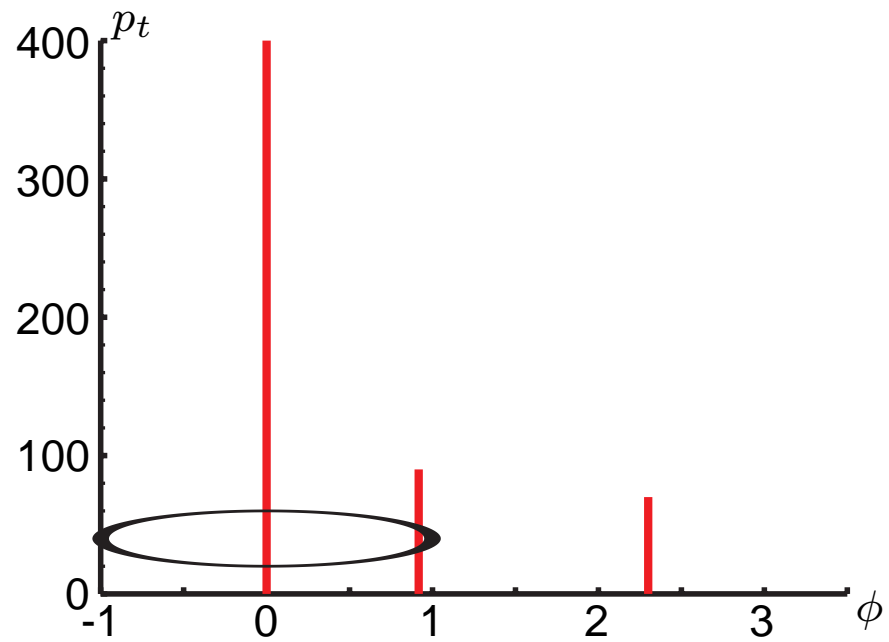


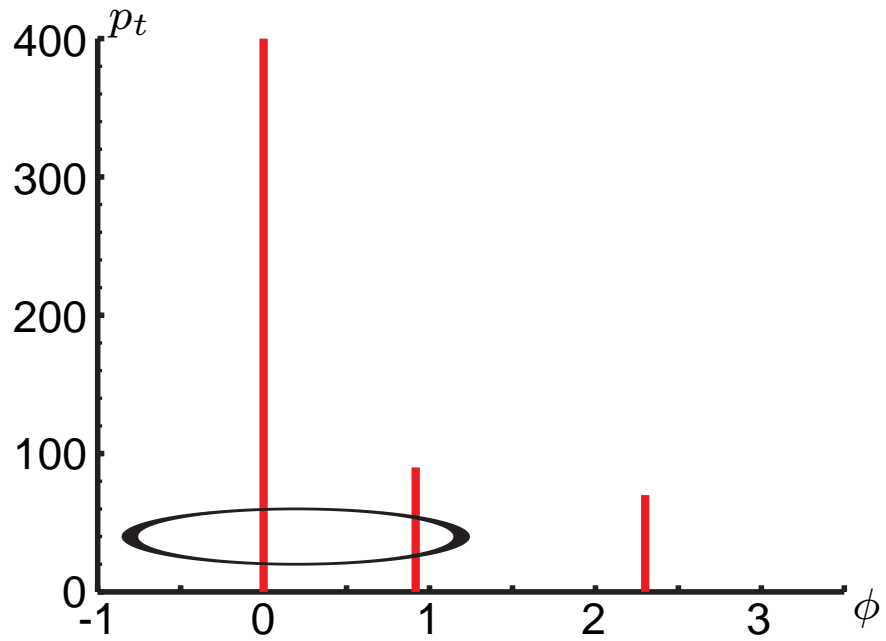
Soft

For pQCD to make sense, the (hard) jets (or stable cones) should not change when

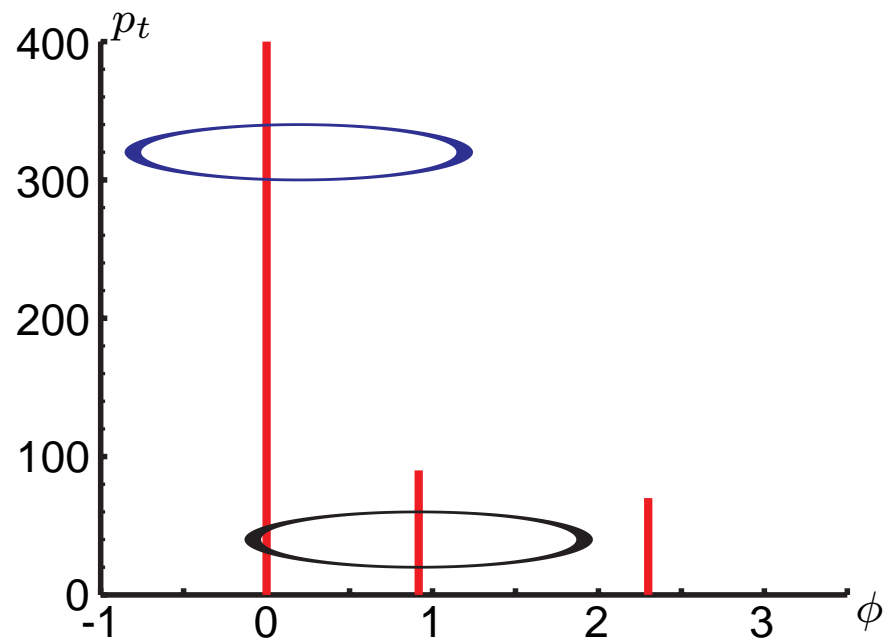
- one has a collinear splitting
i.e. replaces one parton by two at the same place (η, ϕ)
- one has a soft emission *i.e.* adds a very soft gluon



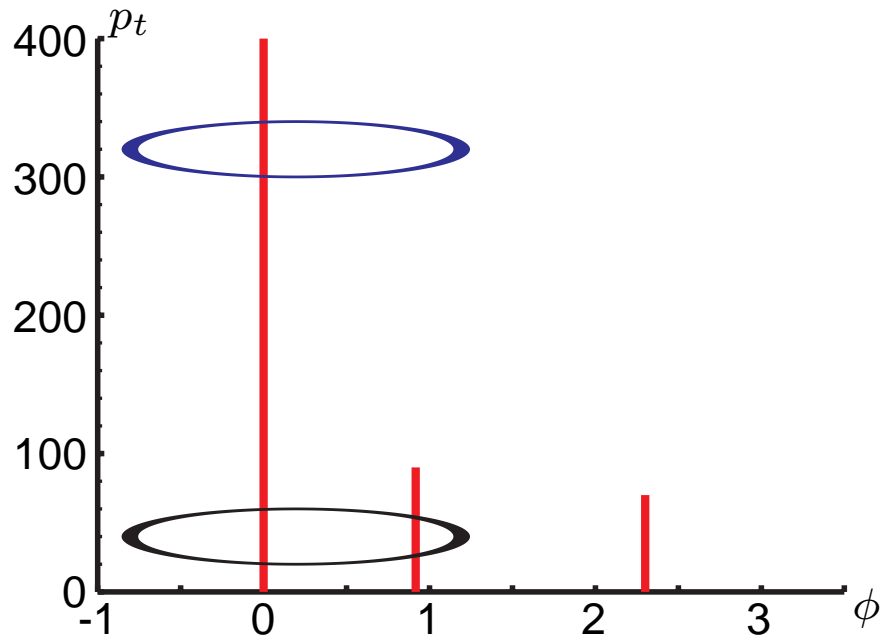


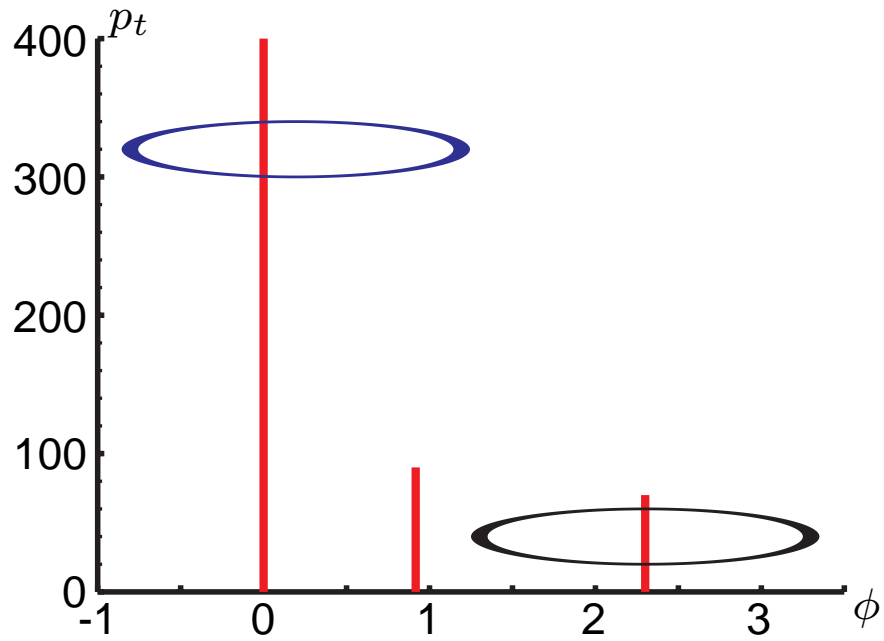


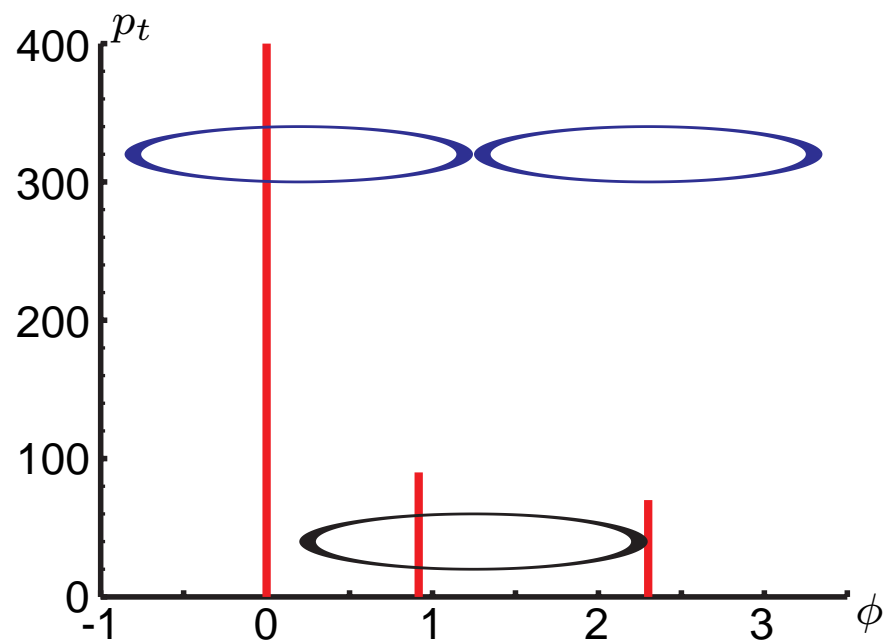
IR unsafety of the Midpoint alg



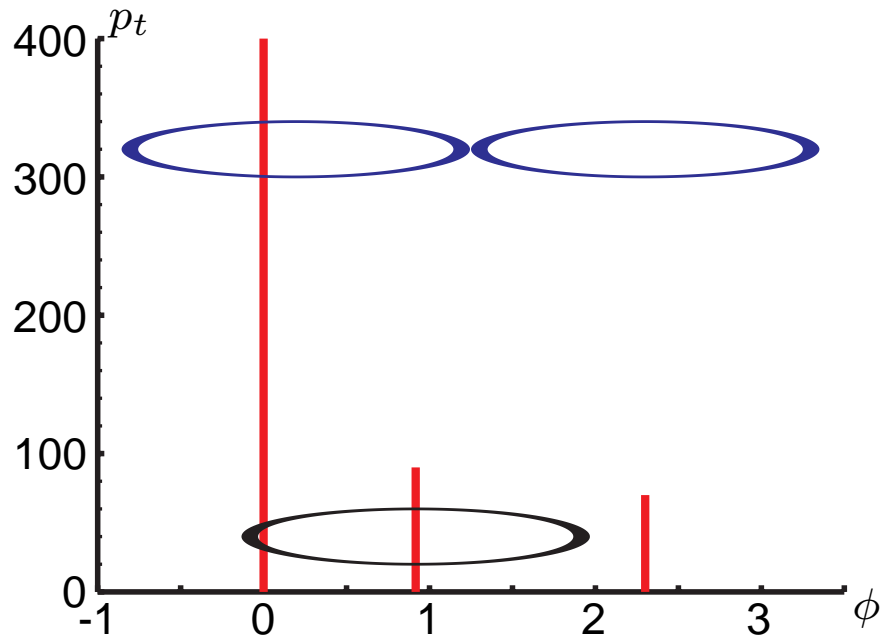
IR unsafety of the Midpoint alg



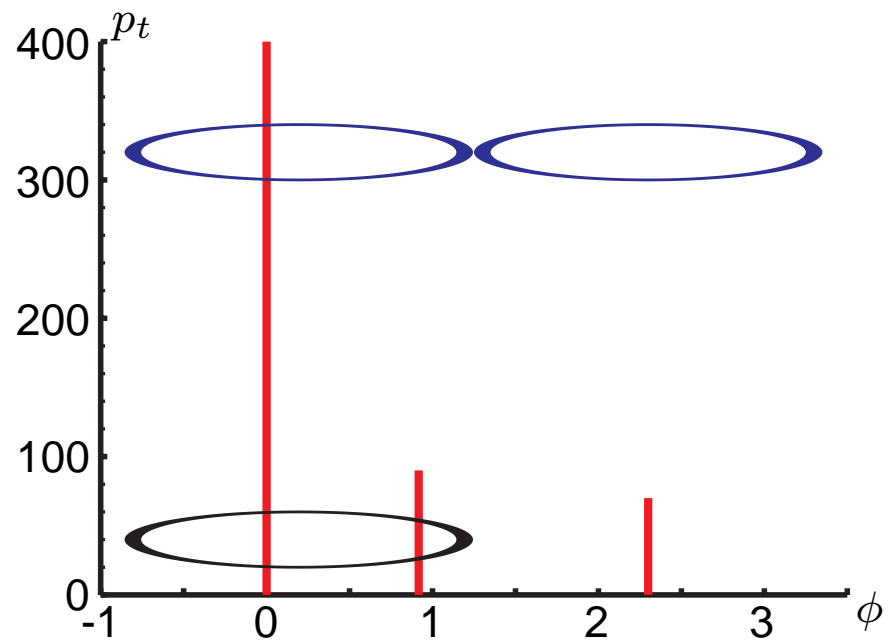




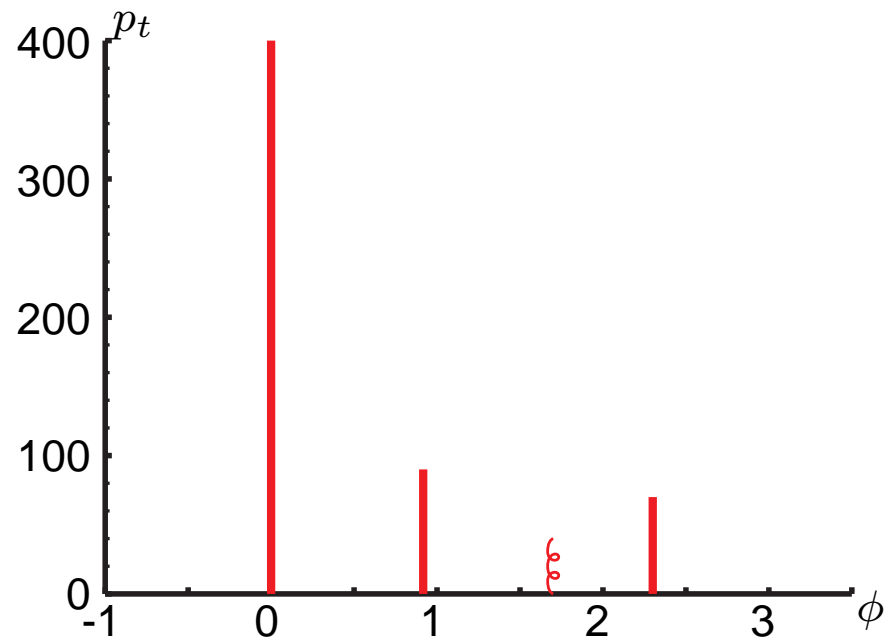
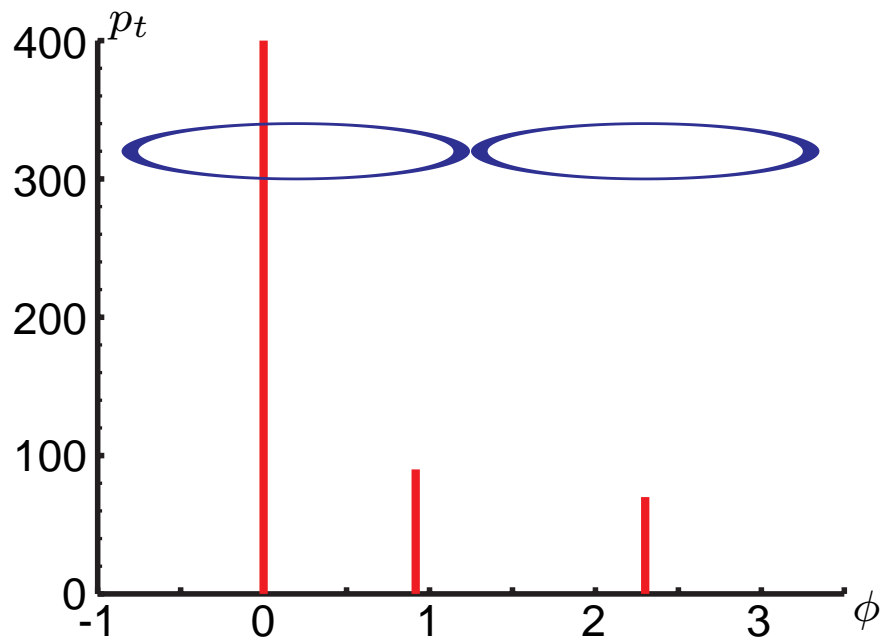
IR unsafety of the Midpoint alg



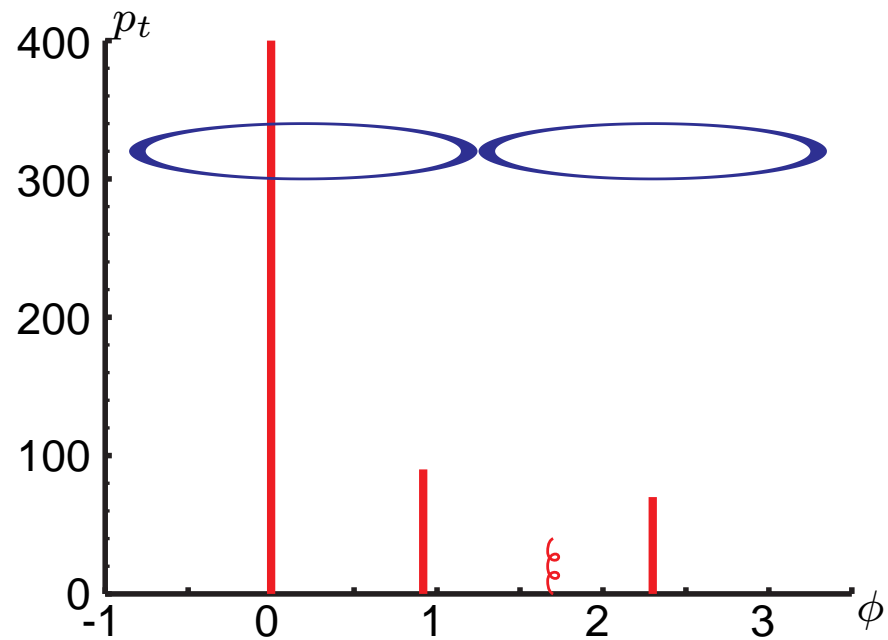
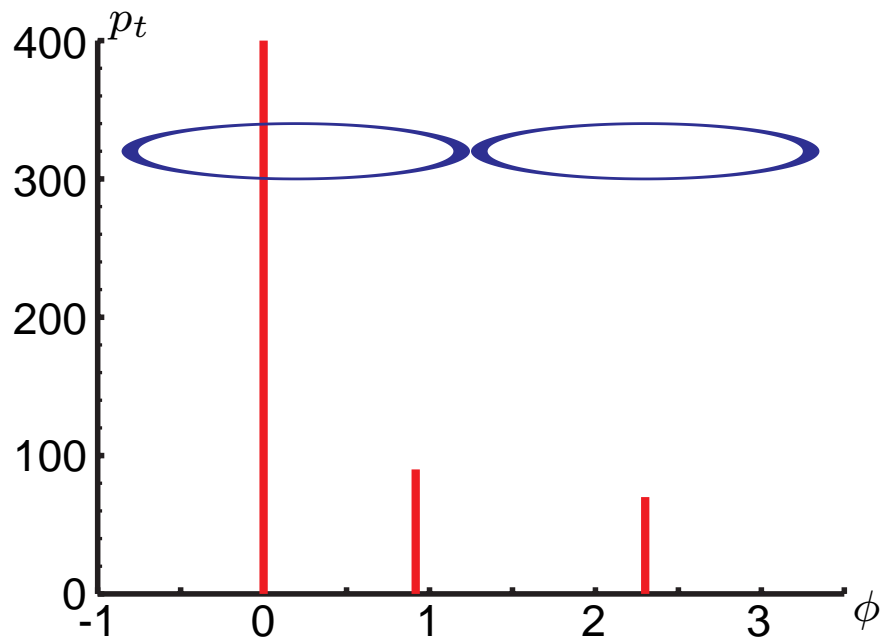
IR unsafety of the Midpoint alg



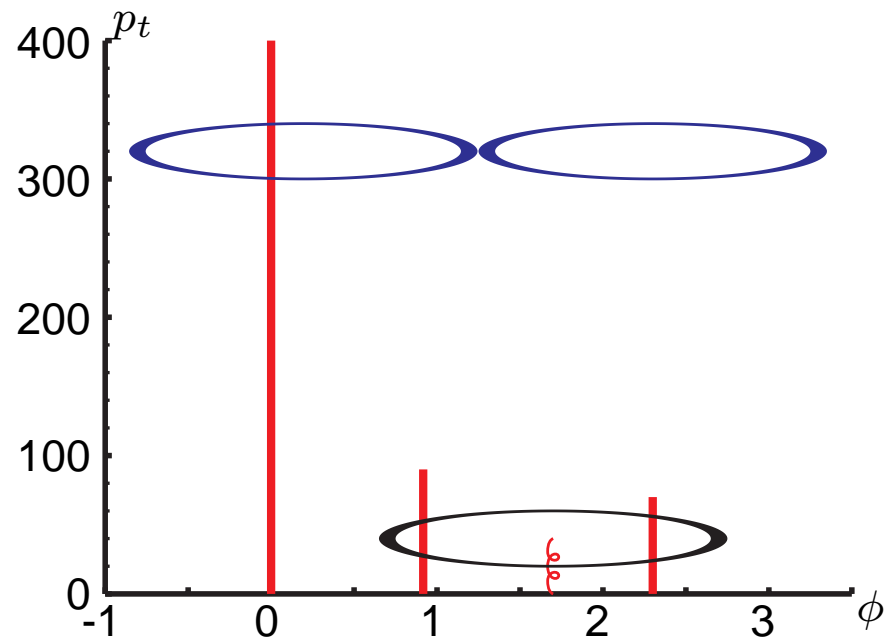
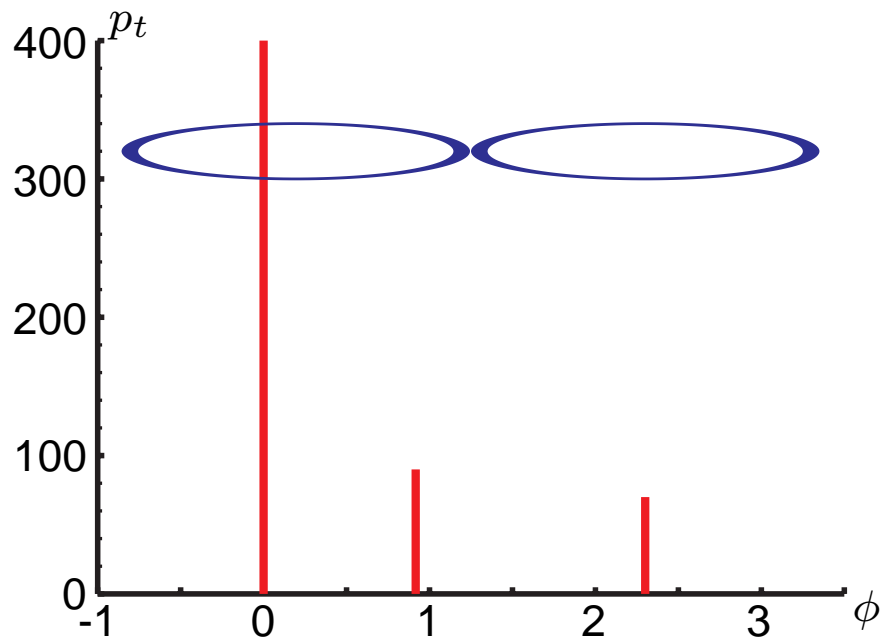
IR unsafety of the Midpoint alg



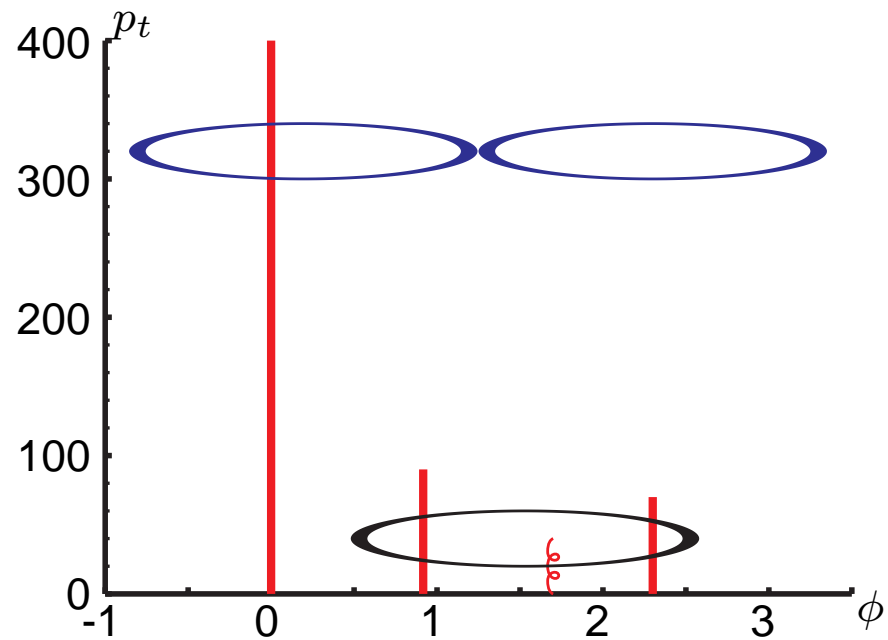
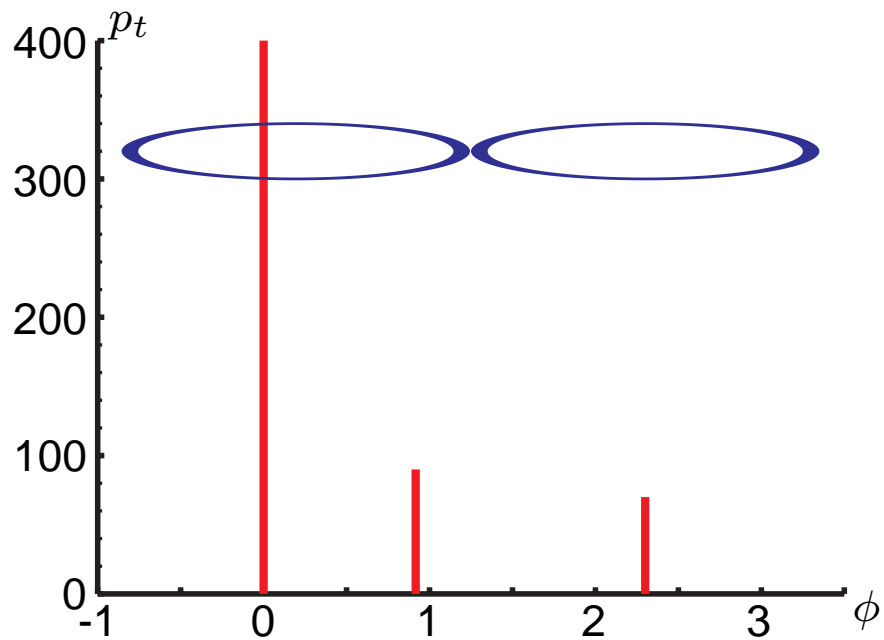
IR unsafety of the Midpoint alg



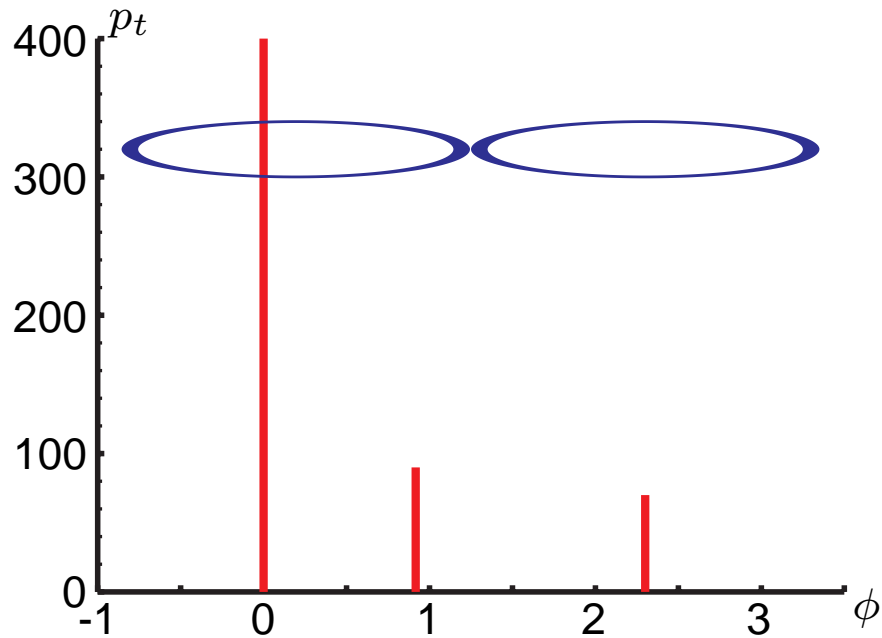
IR unsafety of the Midpoint alg



IR unsafety of the Midpoint alg

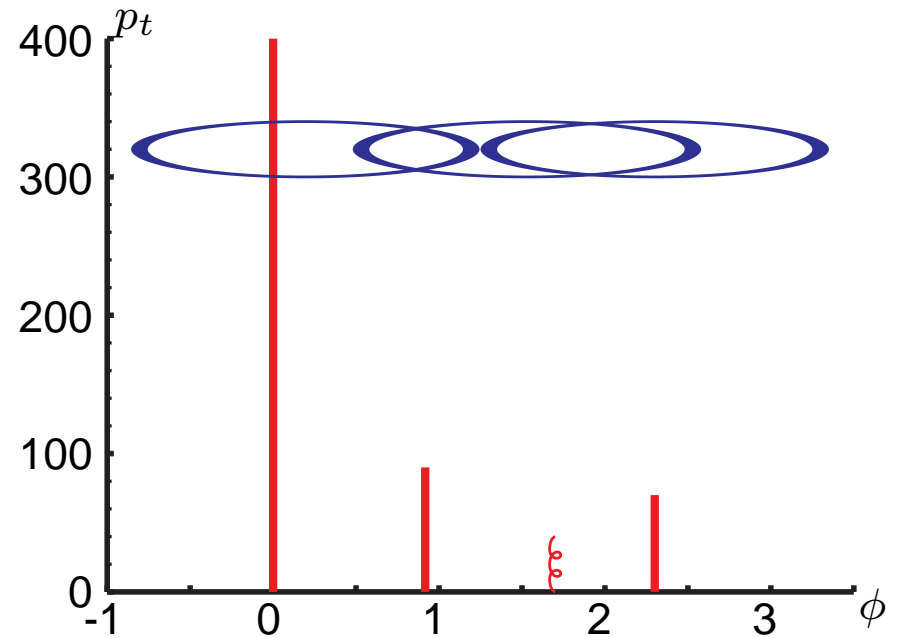


IR unsafety of the Midpoint alg

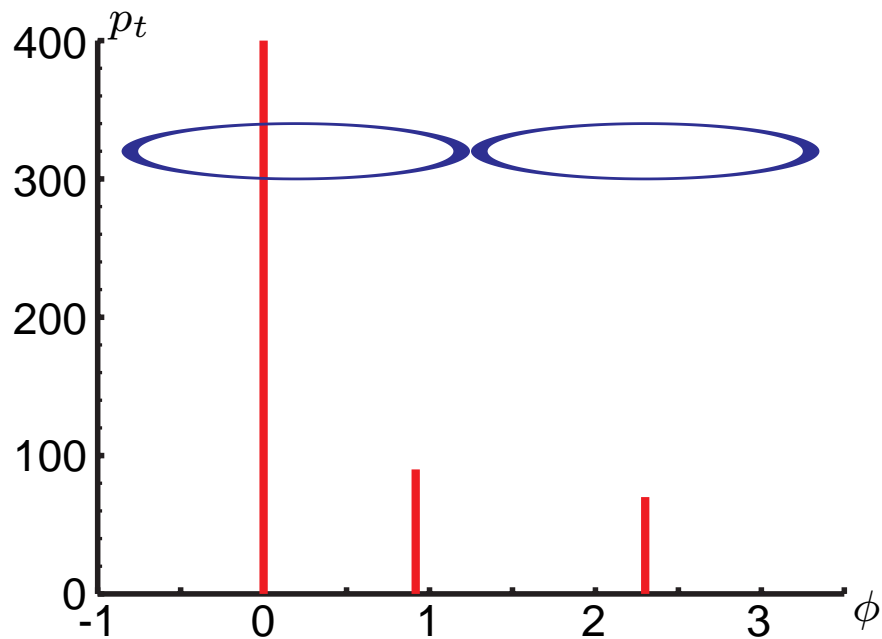


Stable cones:

Midpoint: {1,2} & {3}

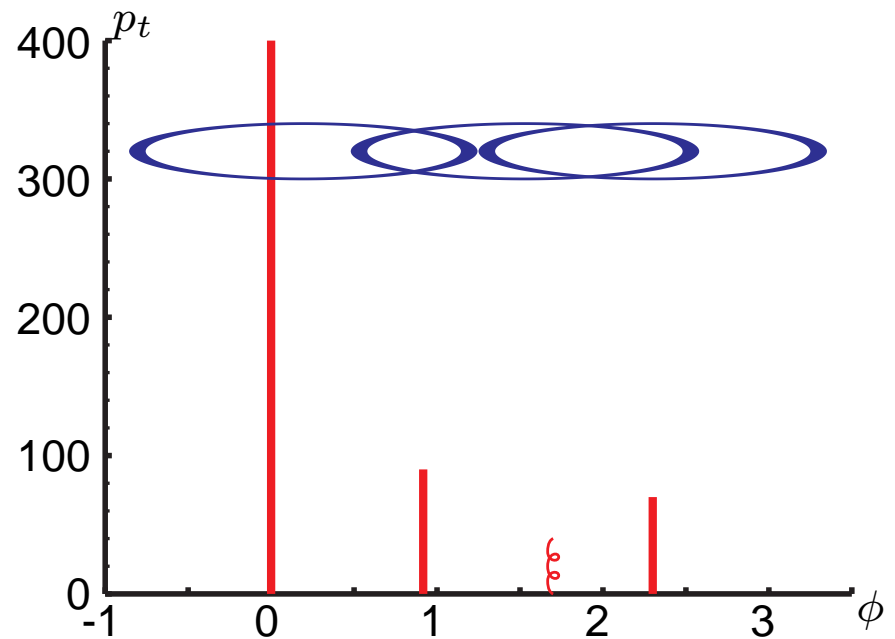


{1,2} & {3} & {2,3}



Stable cones:

Midpoint: {1,2} & {3}

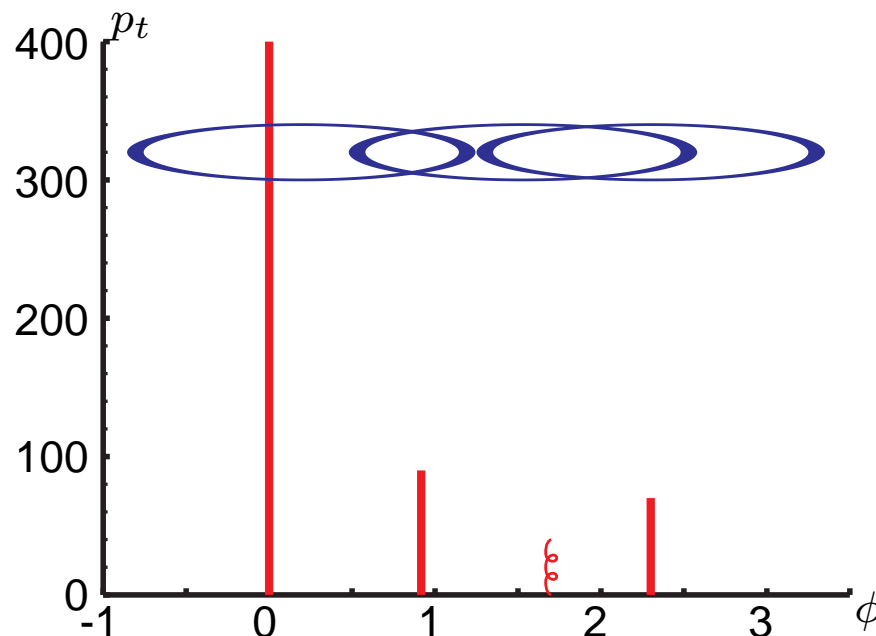
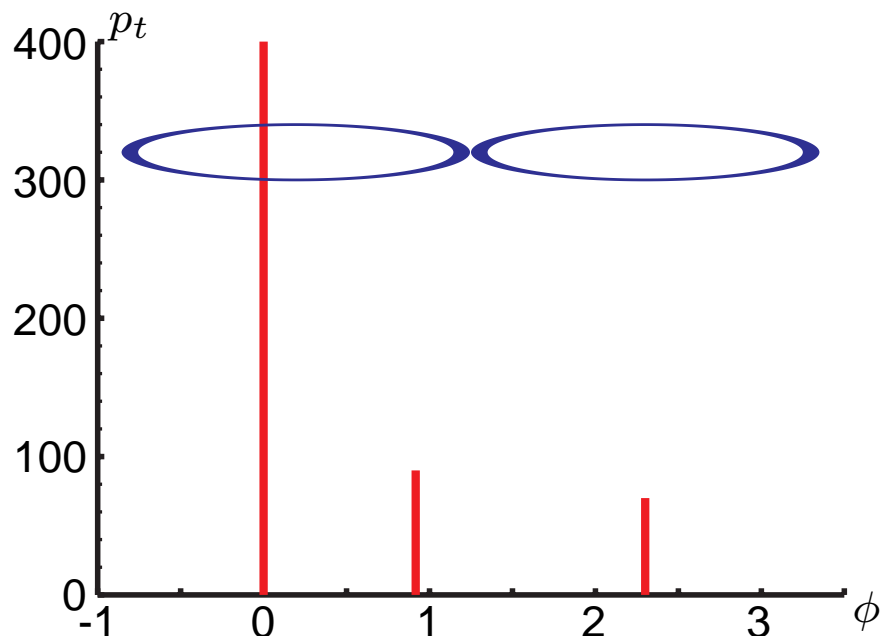


{1,2} & {3} & {2,3}

Jets: ($f = 0.5$)

Midpoint: {1,2} & {3}

{1,2,3}



Stable cones:

Midpoint: {1,2} & {3}

Seedless: {1,2} & {3} & {2,3}

{1,2} & {3} & {2,3}

{1,2} & {3} & {2,3}

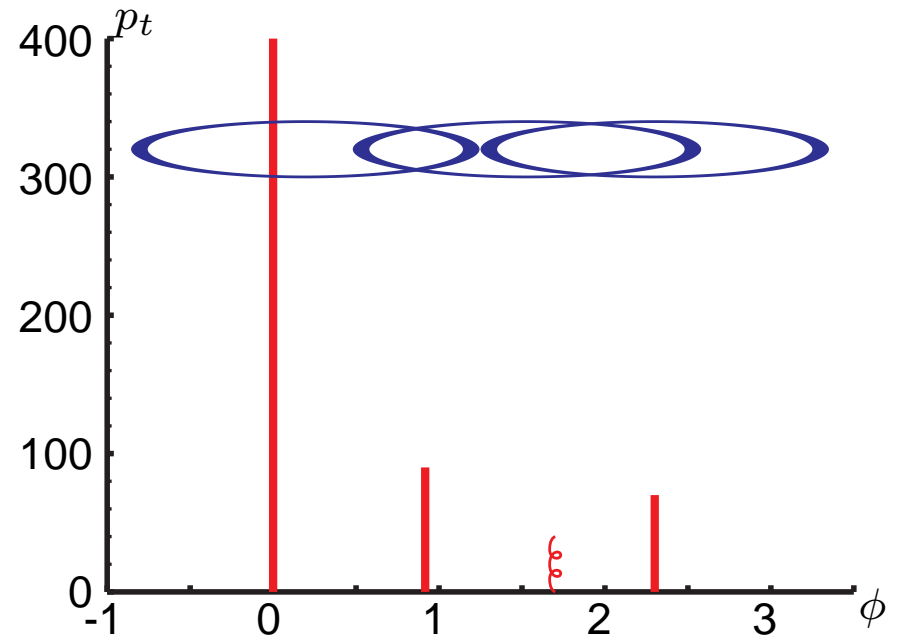
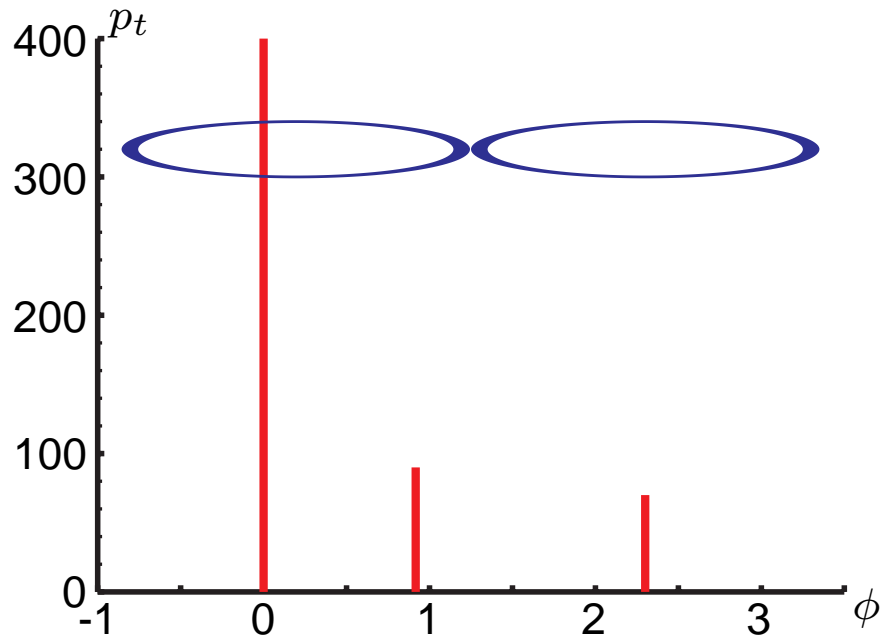
Jets: ($f = 0.5$)

Midpoint: {1,2} & {3}

Seedless: {1,2,3}

{1,2,3}

{1,2,3}



Stable cones:

Midpoint: {1,2} & {3}

Seedless: {1,2} & {3} & {2,3}

{1,2} & {3} & {2,3}

{1,2} & {3} & {2,3}

Jets: ($f = 0.5$)

Midpoint: {1,2} & {3}

Seedless: {1,2,3}

{1,2,3}

{1,2,3}

Stable cone missed \longrightarrow IR unsafety of the midpoint algorithm

- Solution: use a seedless approach, find **ALL** stable cones
- Naive approach: check stability of each subset of particle

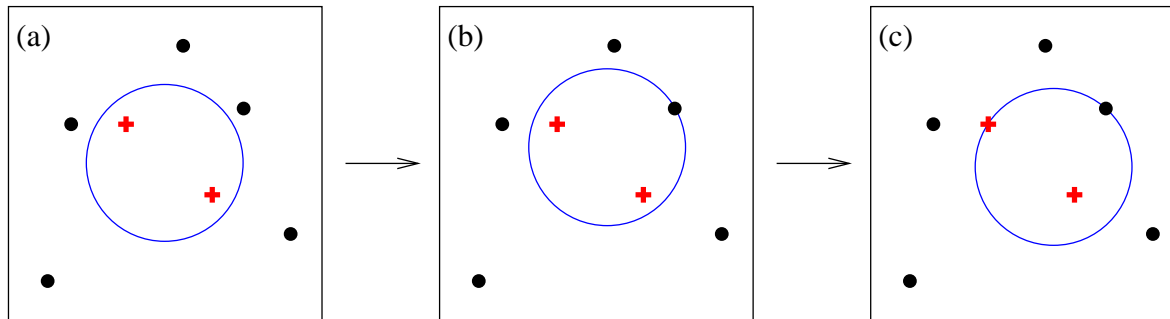
- Solution: use a seedless approach, find **ALL** stable cones
- Naive approach: check stability of each subset of particle
Complexity is $\mathcal{O}(N2^N)$
 \Rightarrow **definitely unrealistic: 10^{17} years for $N = 100$**
- Midpoint complexity: $\mathcal{O}(N^3)$

- Solution: use a seedless approach, find **ALL** stable cones
- Midpoint complexity: $\mathcal{O}(N^3)$

Idea: use geometric arguments

- Solution: use a seedless approach, find **ALL** stable cones
- Midpoint complexity: $\mathcal{O}(N^3)$

Idea: use geometric arguments



- Each enclosure can be moved (in any direction) until it touches a point
- ... then rotated until it touches a second one

- Solution: use a seedless approach, find **ALL** stable cones
- Midpoint complexity: $\mathcal{O}(N^3)$

Idea: use geometric arguments

⇒ Enumerate all pairs of particles
with 2 circle orientations and 4 possible inclusion/exclusion
→ find all enclosures

- Solution: use a seedless approach, find **ALL** stable cones
- Midpoint complexity: $\mathcal{O}(N^3)$

Idea: use geometric arguments

⇒ Enumerate all pairs of particles
with 2 circle orientations and 4 possible inclusion/exclusion
→ find all enclosures

- Complexity: $\mathcal{O}(N^3)$, with improvements: $\mathcal{O}(N^2 \log(N))$

- Solution: use a seedless approach, find **ALL** stable cones
- Midpoint complexity: $\mathcal{O}(N^3)$

Idea: use geometric arguments

⇒ Enumerate all pairs of particles
with 2 circle orientations and 4 possible inclusion/exclusion
→ find all enclosures

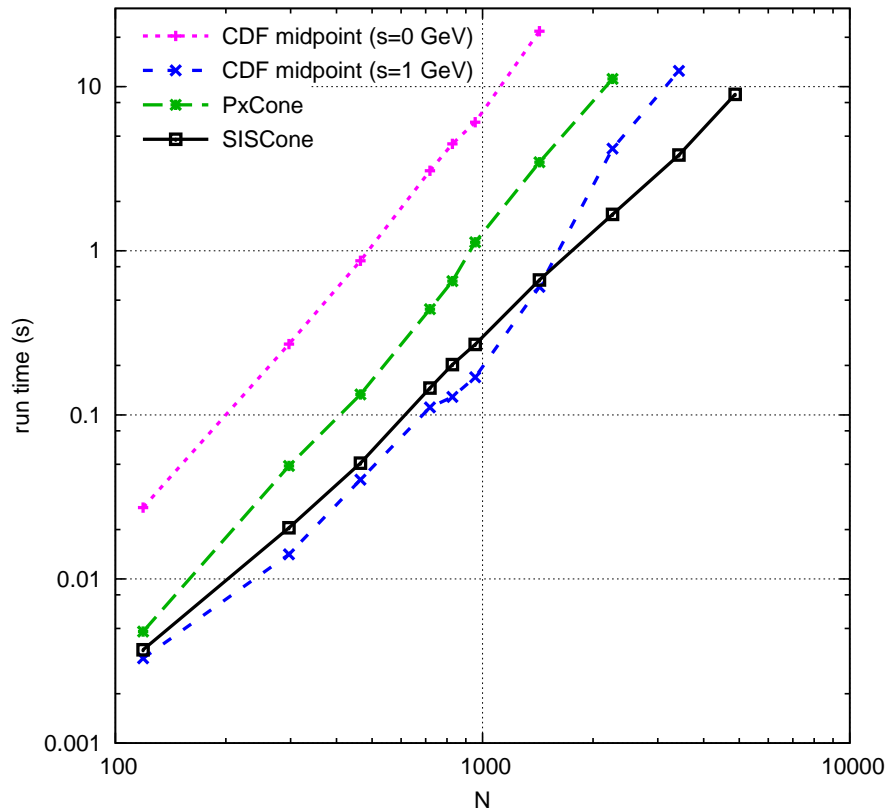
- Complexity: $\mathcal{O}(N^3)$, with improvements: $\mathcal{O}(N^2 \log(N))$

→ C++ implementation: Seedless Infrared-Safe Cone algorithm (SIScone)
G.Salam, G.S., JHEP 04 (2007) 086; <http://projects.hepforge.org/siscone>

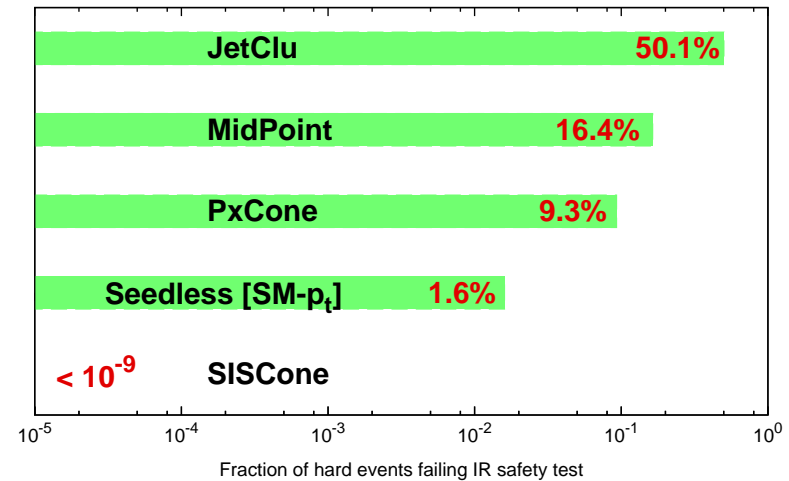
NB.: also available from FastJet

[M.Cacciari, G.Salam, G.S.]; <http://www.lpthe.jussieu.fr/~salam/fastjet>

Execution timings:



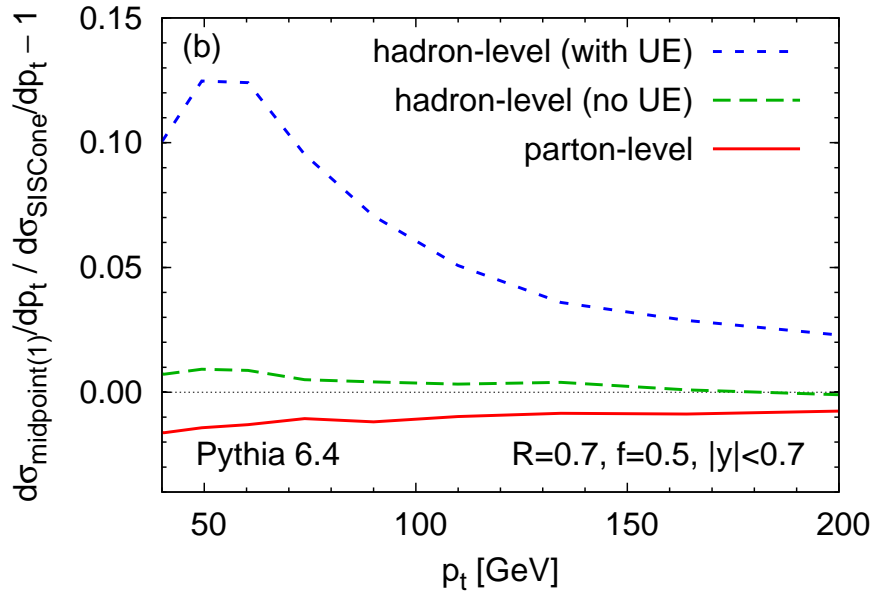
Random hard & soft partons
fraction with “hard \neq hard+soft”



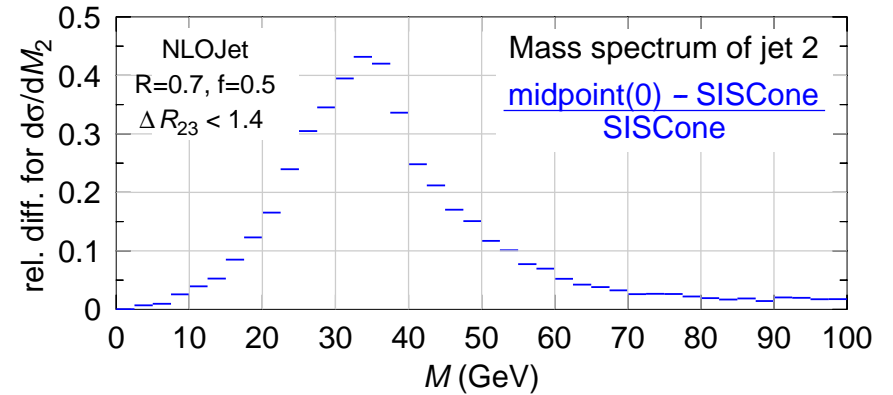
- at least as fast as midpoint cones
- IR safe
 - JetClu, ATLAS cone: 50% failure
 - MidPoint: 15% failure

Inclusive (midpoint/SISCone-1)

pp $\sqrt{s} = 14$ TeV



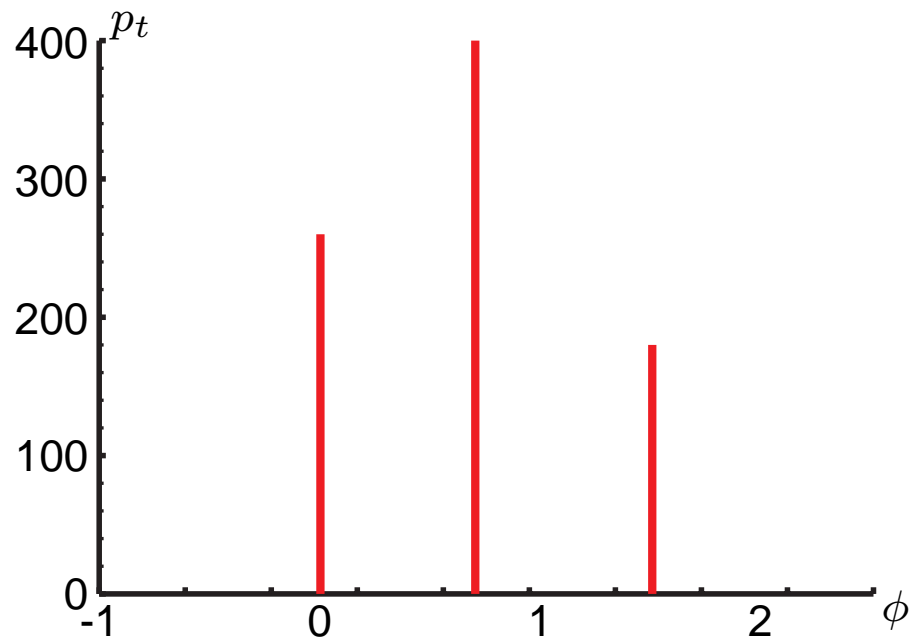
Masses in 3-jet events

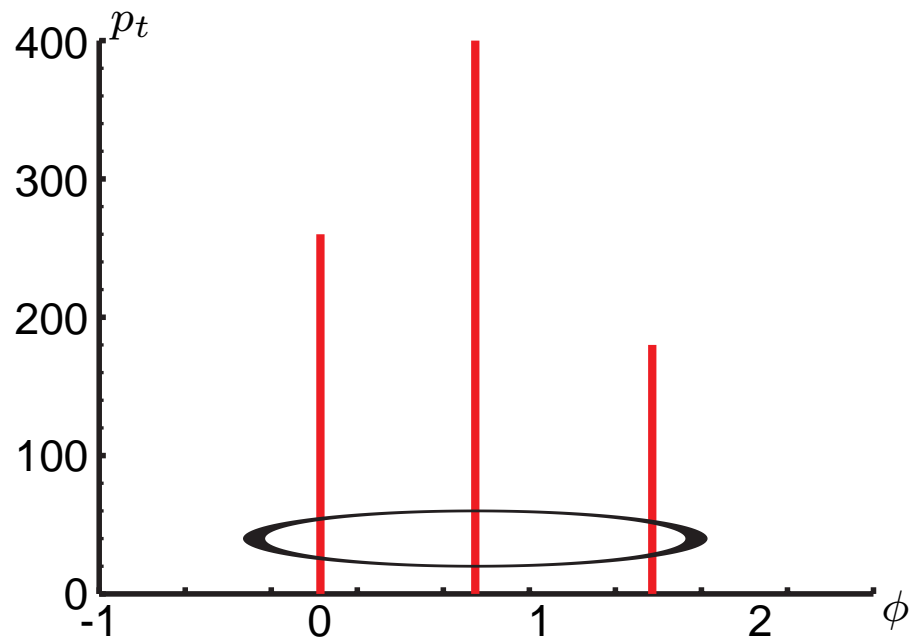


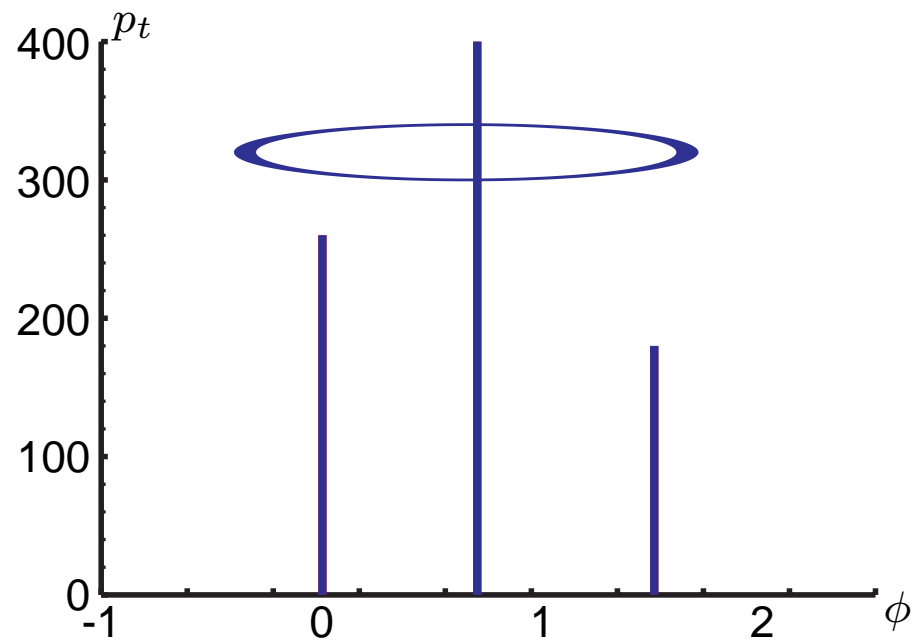
Inclusive cross-section:

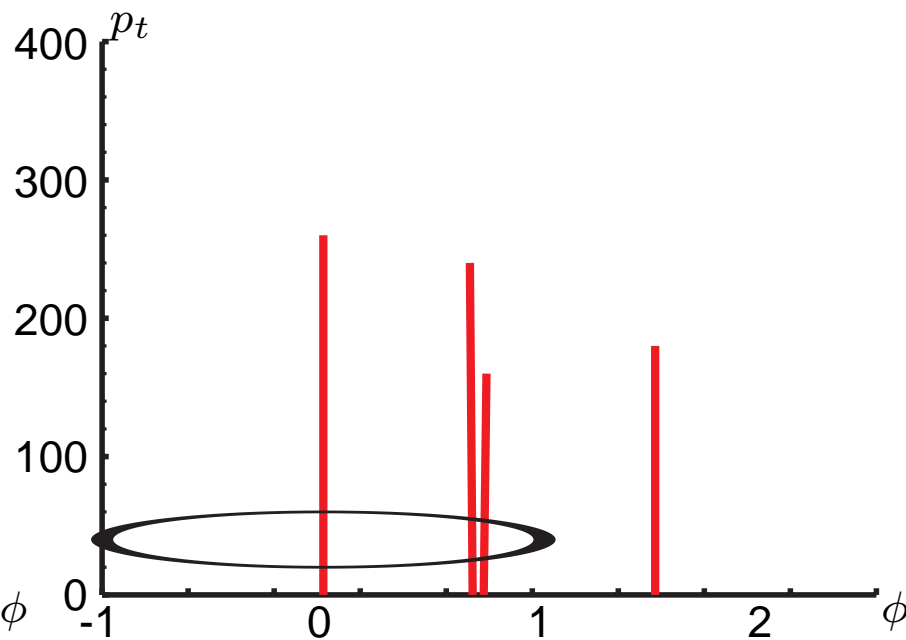
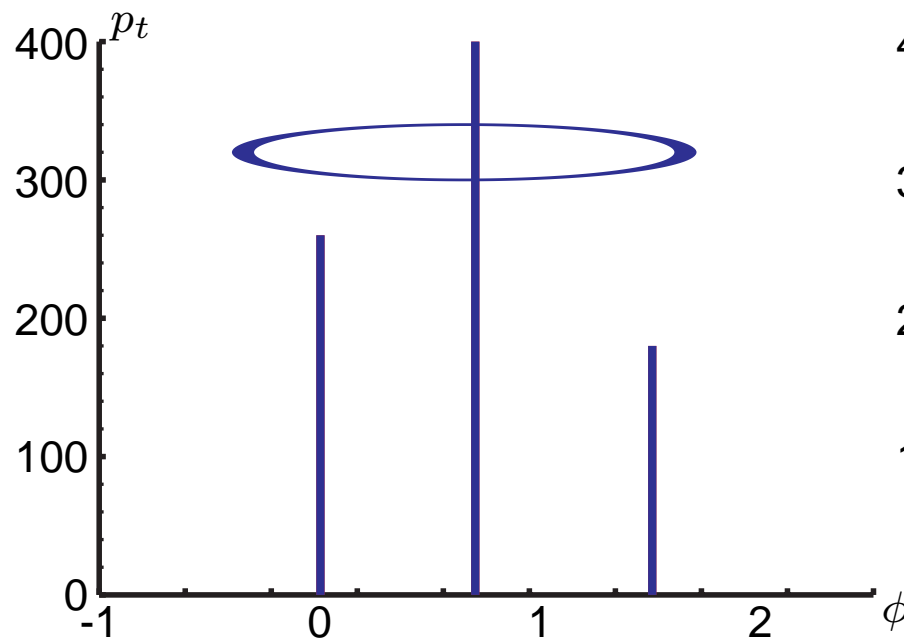
- Effect of a few percents
- Less sensitivity to the UE

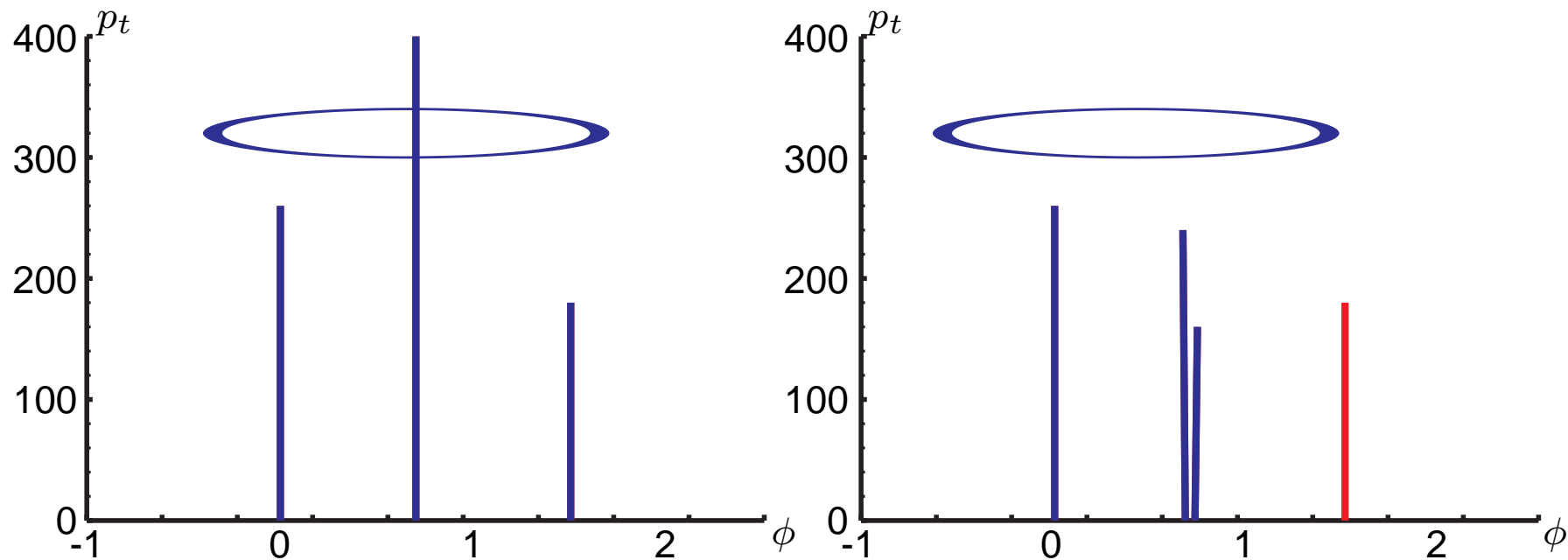
• More exclusive processes: effects $\sim 45\%$ (Important for LHC!)

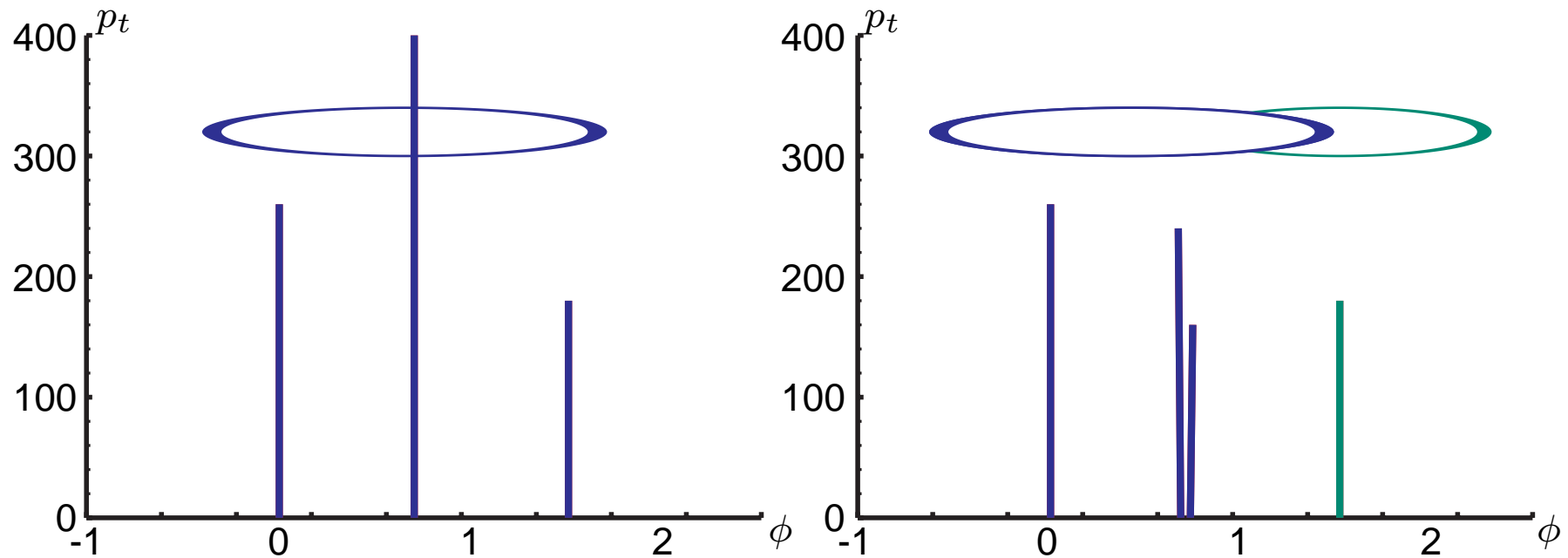


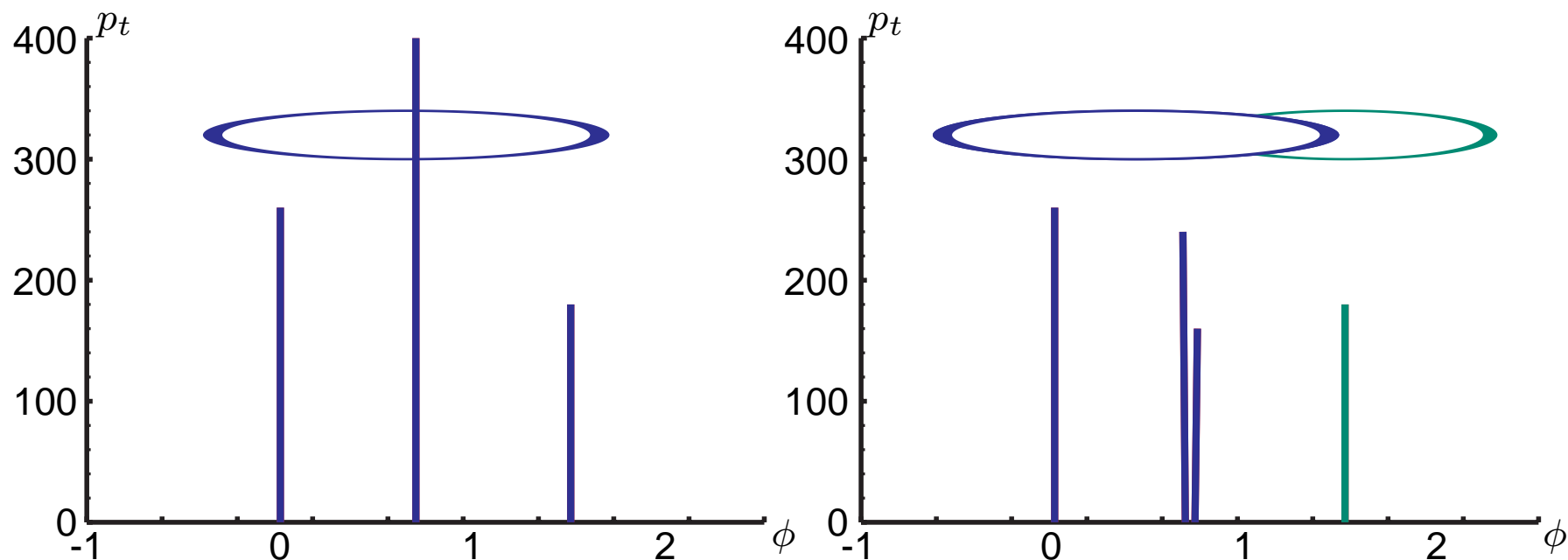












- Before collinear splitting: 1 jet
- After collinear splitting: 2 jets

→ **collinear unsafety of the iterative cone algorithm**

Come back to recombination-type algorithms:

$$d_{ij} = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) (\Delta\phi_{ij}^2 + \Delta\eta_{ij}^2)$$

- $p = 1$: k_t algorithm
- $p = 0$: Aachen/Cambridge algorithm

Come back to recombination-type algorithms:

$$d_{ij} = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) (\Delta\phi_{ij}^2 + \Delta\eta_{ij}^2)$$

- $p = 1$: k_t algorithm
- $p = 0$: Aachen/Cambridge algorithm
- $p = -1$: anti- k_t algorithm [M.Cacciari, G.Salam, G.S., JHEP 04 (08) 063]

Come back to recombination-type algorithms:

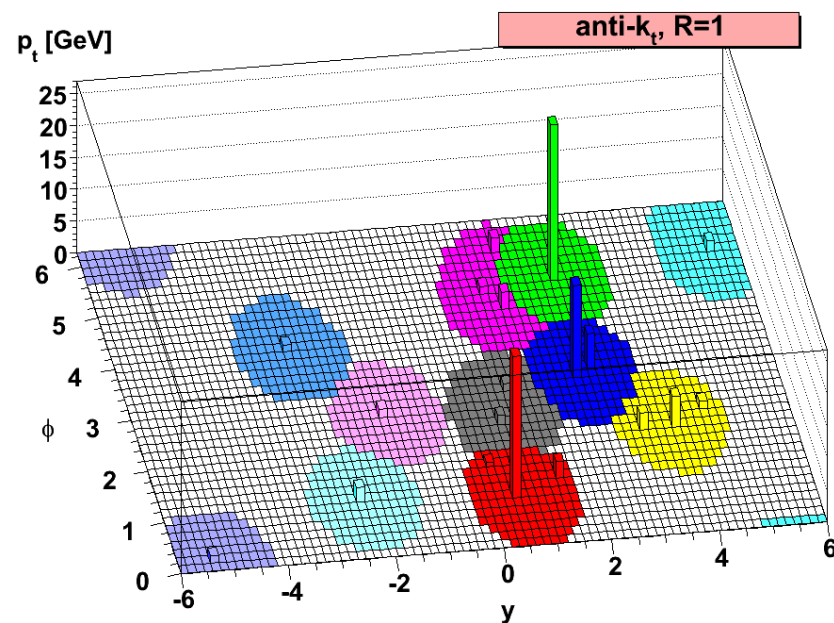
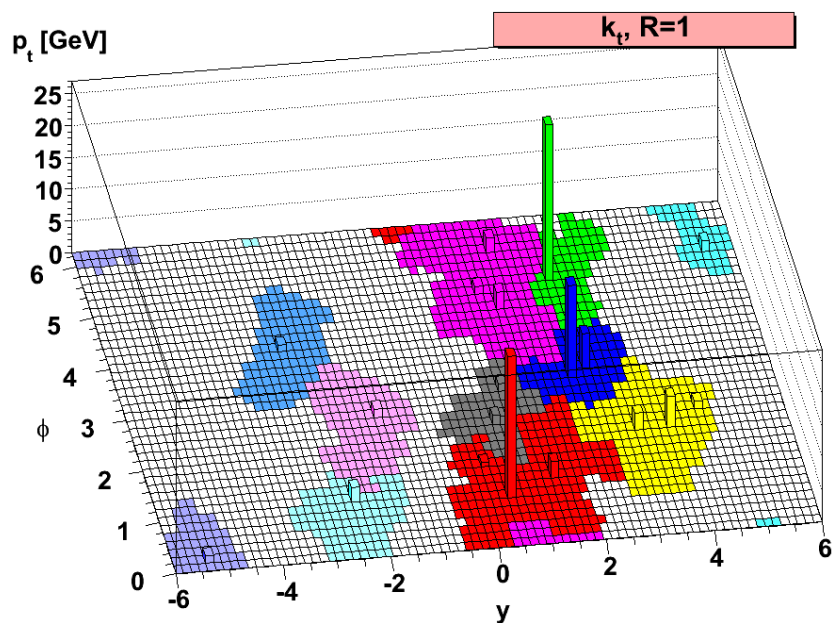
$$d_{ij} = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) (\Delta\phi_{ij}^2 + \Delta\eta_{ij}^2)$$

- $p = 1$: k_t algorithm
- $p = 0$: Aachen/Cambridge algorithm
- $p = -1$: anti- k_t algorithm [M.Cacciari, G.Salam, G.S., JHEP 04 (08) 063]

Why should that be related to the iterative cone ?!?

- “large $k_t \Rightarrow$ small distance”
i.e. hard partons “eat” everything up to a distance R
i.e. circular/regular jets, jet borders unmodified by soft radiation
- infrared and collinear safe

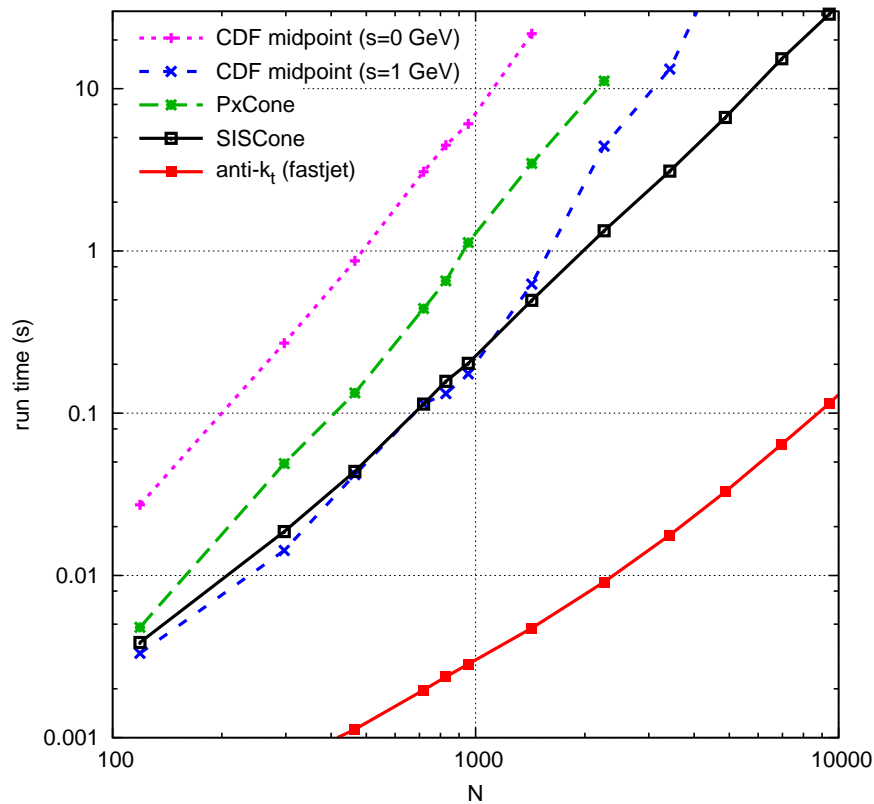
Hard event + homogeneous soft background



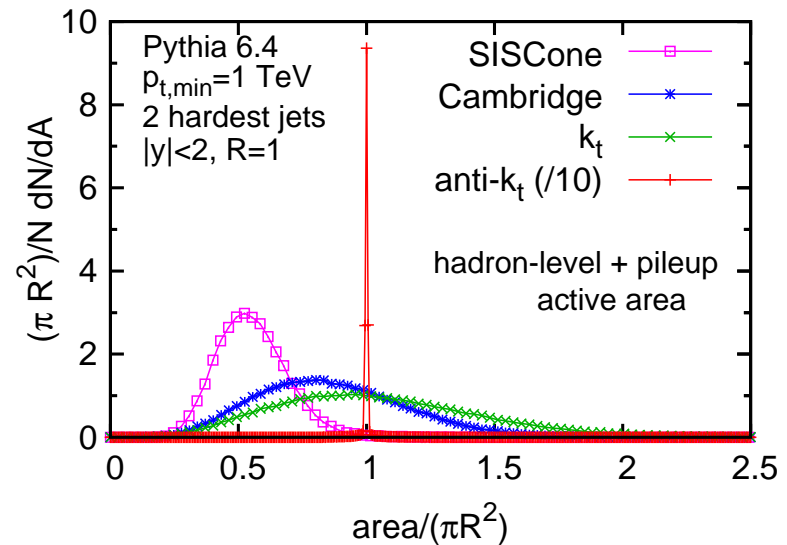
anti- k_t is soft-resilient

more in Matteo Cacciari's talk...

Execution timings:



Distribution of hard jets area



- As fast as the (fast) k_t ([M. Cacciari, G. Salam, 06])
- Regular hard jets of area πR^2

Midpoint and the iterative cone IR or Collinear unsafe (at $\mathcal{O}(\alpha_s^4)$)

Observable	1st miss cones at	Last meaningful order
Inclusive jet cross section	NNLO	NLO
3 jet cross section	NLO	LO (NLO in NLOJet)
$W/Z/H + 2$ jet cross sect.	NLO	LO (NLO in MCFM)
jet masses in 3 jets	LO	none (LO in NLOJet)

⇒ The IR-unsafety issue will matter at LHC

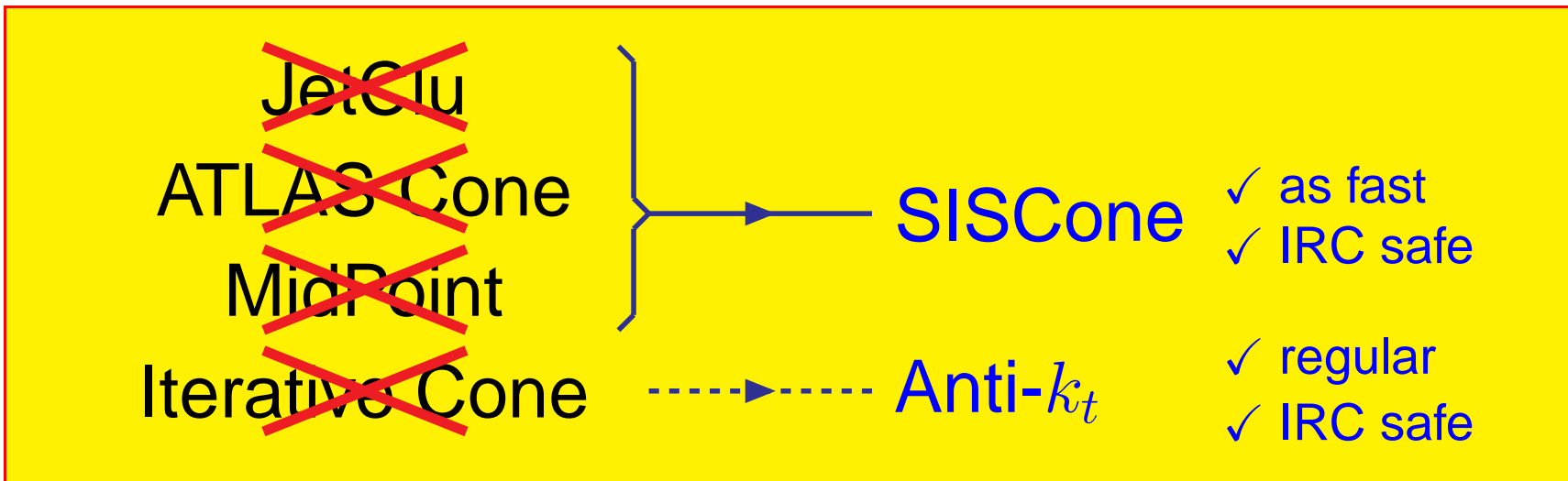
+ We do not want the theoretical efforts to be wasted

Midpoint and the iterative cone IR or Collinear unsafe (at $\mathcal{O}(\alpha_s^4)$)

Observable	1st miss cones at	Last meaningful order
Inclusive jet cross section	NNLO	NLO
3 jet cross section	NLO	LO (NLO in NLOJet)
$W/Z/H$ + 2 jet cross sect.	NLO	LO (NLO in MCFM)
jet masses in 3 jets	LO	none (LO in NLOJet)

⇒ The IR-unsafety issue will matter at LHC

+ We do not want the theoretical efforts to be wasted



Both available from FastJet (<http://www.lpthe.jussieu.fr/~salam/fastjet>)